

# Accurate field saturated hydraulic conductivity—Why is it so difficult?

# Why K<sub>fs</sub> is a pain

Saturated hydraulic conductivity, or the ability of soil to absorb water, has traditionally been a complex measurement for scientists to make. Inaccurate field saturated hydraulic conductivity ( $K_{fs}$ ) measurements are common due to errors in soil-specific alpha estimation and inadequate three-dimensional flow buffering. Three-dimensional flow means water infiltrates the soil in three dimensions; it spreads laterally, as well as downward. The problem is, the value which represents saturated hydraulic conductivity,  $K_{fs}$ , is a one-dimensional value. Researchers use  $K_{fs}$  in modeling as the basis of their decision making, but to get that value, they must first remove the effects of three-dimensional flow.

## Estimation—a risky proposition

The traditional method for removing the effects of three-dimensional flow is to look at a table of alpha values or the soil macroscopic capillary length. But since alpha is only an *estimate* of the sorptivity effect, or how much the soil is going to pull the water laterally, the risk of inaccuracy is high. And if a researcher or engineer chooses the wrong alpha value, their estimate could be significantly off.

To get around this problem, researchers sometimes measure  $K_{ts}$  with a double-ring infiltrometer (Figure 2), a simple method where the outer ring is intended to limit the lateral spread of water after infiltration and buffer three-dimensional flow. However, a double-ring infiltrometer does not buffer three-dimensional flow perfectly (Swartzendruber D. and T.C. Olson 1961a). So if researchers operate on the assumption that they're getting onedimensional flow in the center ring, they may overestimate their field saturated conductivity values. This can be disastrous, particularly when working with a soil that has been engineered to have a very low permeability. If  $K_{ts}$  is overestimated, a researcher or engineer could incorrectly assume a landfill cover (for example) is ineffective ( $K_s$  is over 10<sup>-5</sup> cm s<sup>-1</sup>), when in reality, they've overestimated  $K_{ts}$ , and the cover is actually compliant.

# K<sub>fs</sub>—solved

The SATURO eliminates the estimation/assumption problem by automating the wellestablished *dual head* method. It ponds water on top of the soil and uses air pressure to create two different pressure heads. Measuring infiltration at these two different pressure heads avoids the need for estimating the alpha factor, enabling researchers to determine field saturated hydraulic conductivity without making any assumptions. Additionally, the SATURO uses *much* less water because it doesn't require a large outer ring like a double ring infiltrometer. This automated approach saves time and reduces error in the hydraulic conductivity assessment. The following theory section explains in detail why this is possible.

The science behind the SATURO automated dual head infiltrometer includes:

- What is hydraulic conductivity?
- Porous mediums
- What determines hydraulic conductivity
- Why you should care about hydraulic conductivity
- How is hydraulic conductivity measured?
- Lab instruments
- Field instruments
- The method behind SATURO: dual head infiltrometer
- Comparison: Double-ring and SATURO dual-head methods

### SATURO: Why it's more accurate

Field saturated hydraulic conductivity,  $K_{fs}$  (cm/s) is a fundamental soil hydraulic property that describes the ease with which a fluid (usually water) can move through pore spaces or fractures under field saturated conditions. One of the oldest and simplest methods for in situ determination of  $K_{fs}$  has involved the measurement of ponded infiltration (*D*) from within a single ring (with a radius *b*) pushed a small distance into the soil (*d*) (Figure 1). The original analysis used the measured steady flow rate, *Qs* (cm3/s) and assumed one-dimensional, vertical flow to obtain  $K_{fs}$  from Bouwer (1986) and Daniel (1989).



Figure 1. Cross section of a single-ring infiltrometer

This approach overestimated  $K_{s}$  due to lateral divergence of flow resulting from the capillarity of the unsaturated soil and from the ponding in the ring (Bouwer 1986). Attempts to eliminate flow divergence involved the addition of an outer ring to buffer the flow in the inner ring (Figure 2). However, the double-ring infiltrometer technique was ineffective at preventing lateral flow from the inner ring (Swartzendruber and Olson 1961a, 1961b).



Figure 2. Cross section of a double-ring infiltrometer

More recent research provides new methods for correcting for lateral flow. Reynolds and Elrick (1990) presented a new analysis method of steady ponded infiltration into a single ring, which accounts for soil capillarity, depth of ponding, ring radius (*b*), and depth of ring insertion (*d*) and provides a means for calculating  $K_{s}$ , matric flux ( $\varphi m$ ), and macroscopic capillary length ( $\alpha$ ). This analysis is known as the two-ponding head approach (Reynolds and Elrick 1990).

The two-ponding head approach is the technique used by SATURO, though with some modifications and simplifications. The simplest equation for this calculation is from Nimmo et al. (2009). They compute  $K_{s}$  as shown in Equation 1.

$$K_{fs} = \frac{i}{F}$$



where i (cm/s) is the steady (final) infiltration rate (volume divided by area) and F is a function that corrects for sorptivity and geometrical effects.

Nimmo et al. (2009) gives F as shown in Equation 2

$$F = 1 + \frac{\lambda + D}{C_1 d + C_2 b} = 1 + \frac{\lambda + D}{\Delta}$$

Equation 2

where

- *D* is the ponding depth (cm)
- *d* is the insertion depth of the infiltrometer (cm)
- *b* is the radius of the infiltrometer (cm)
- $\Delta$  is the constant for a given infiltrometer geometry;  $C_1d + C_2b$  (cm)
- *C*<sup>1</sup> is 0.993
- C<sub>2</sub> is 0.578
- λ is the reciprocal of the Gardner ∝, which is a characteristic of the soil and its initial water content (cm)

In Equation 2,  $\Delta$  is simply Equation 36 of Reynolds and Elrick (1990) multiplied by  $b\pi$ , which allows Figure 2 and Equation 2 to be reconciled with Equation 37 of Reynolds and Elrick (1990).

For two ponding depths, use Equation 3:



Equation 3

Rearranging one of the right terms to solve for  $\lambda$  in terms of  $K_{s}$ , substituting this for  $\lambda$  in the other right term, and simplifying yields

$$K_{fs} = \frac{\Delta (i_1 - i_2)}{D_1 - D_2}$$

Equation 4

where

- $D_1$  is the actual high pressure head
- $D_2$  is the actual low pressure head
- ∆ is 0.993d + 0.578b (cm)
- $i_1$  is infiltration rate at the high pressure head
- $i_2$  is infiltration rate at the low pressure head

For  $\Delta$ , *d* is the infiltrometer insertion depth and *b* is the infiltrometer radius. For the SATURO,

5-cm insertion ring, d = 5 cm and b = 7.5 cm, so  $\Delta = 9.3$  cm. For the 10-cm insertion ring, d = 10 cm and b = 7.5 cm, so  $\Delta = 14.3$  cm.

The hydraulic conductivity is then multiplied by the difference in quasi-steady state infiltration rate for the last pressure cycle and divided by the difference in the measured pressure head from the last pressure cycle.

Equation 4 is equivalent to Equation 41 from Reynolds and Elrick (1990) and removes the dependence on soil characteristics and initial water content described by  $\lambda$ .

### Save hours of tedious manual labor

The SATURO combines automation and simplified data analysis together in one system. It even computes infiltration rates and field saturated hydraulic conductivity on the fly. The SATURO makes life a little easier for those who need a faster, more accurate way to measure  $K_{\rm fs}$  in the field.

#### References

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